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Serial Comanipulation for Laparoscopic Surgery

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Minimally Invasive Surgery & Laparoscopy





4 DoF Instruments used in Laparoscopy



Advantages and Disadvantages of Laparoscopy

Advantages (for the Patient)

- •Fewer scars
- Less post operation pain
- •Faster recovery
- Less post operation complications

Disadvantages (for the surgeon)

- Non dexterous instruments
- •Hand eye coordination problem
- Longer operation time

Teleoperation



« da Vinci Surgical System » is a robot for teleoperation.

Teleoperation

da Vinci's 6 DoF instruments give the surgeon the dexterity he needs.



Teleoperation

Teleoperation resolves the Problem of hand eye coordination.





da Vinci's Advantages & Disadvantages

Advantages

- •Dexterous instruments
- Intuitive hand eye coordination
- •Ergonomic interface

Disadvantages

- •High cost: \$ 1.5 to 1.75 M + maintenance and training costs
- •Bulky
- Long and difficult to put in place
- No haptic feedback
- •Surgeon is far from the patient

Serial Comanipulators

RealHand from Novare Surgical

-Has had some success in single incision laparoscopy

-Not useful for precise operations -Effector has low stall torque -Costs \$ 400 and it's disposable -Non intuitive control results in a long learning curve



Robotic Serial Comanipulators

Robot developped at Toshiba Medical Systems

Heavy and big: not usable for surgeons



Towards an Optimal Comanipulator

- •Dextrous
- •Precise
- Lightwheight
- •Ergonomic interface
- •Affordable
- Modular
- •Easy to put in place

Towards an Optimal Comanipulator

Challenges

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i. Finding the best way of coupling the surgeon's gestures to the end effector's movements

ii. Mechanical design and realization

Simulator



Test & Evaluation



Simulating a suturing movement. Suturing includes all elemantry gestures in laparoscopy.



i. Completing the evaluationsii. Making a prototype to validate simulation results

Thank you for your attention.